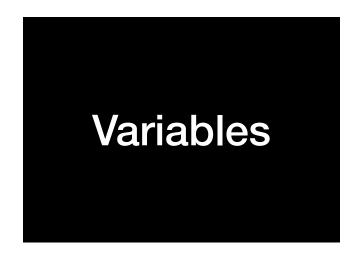
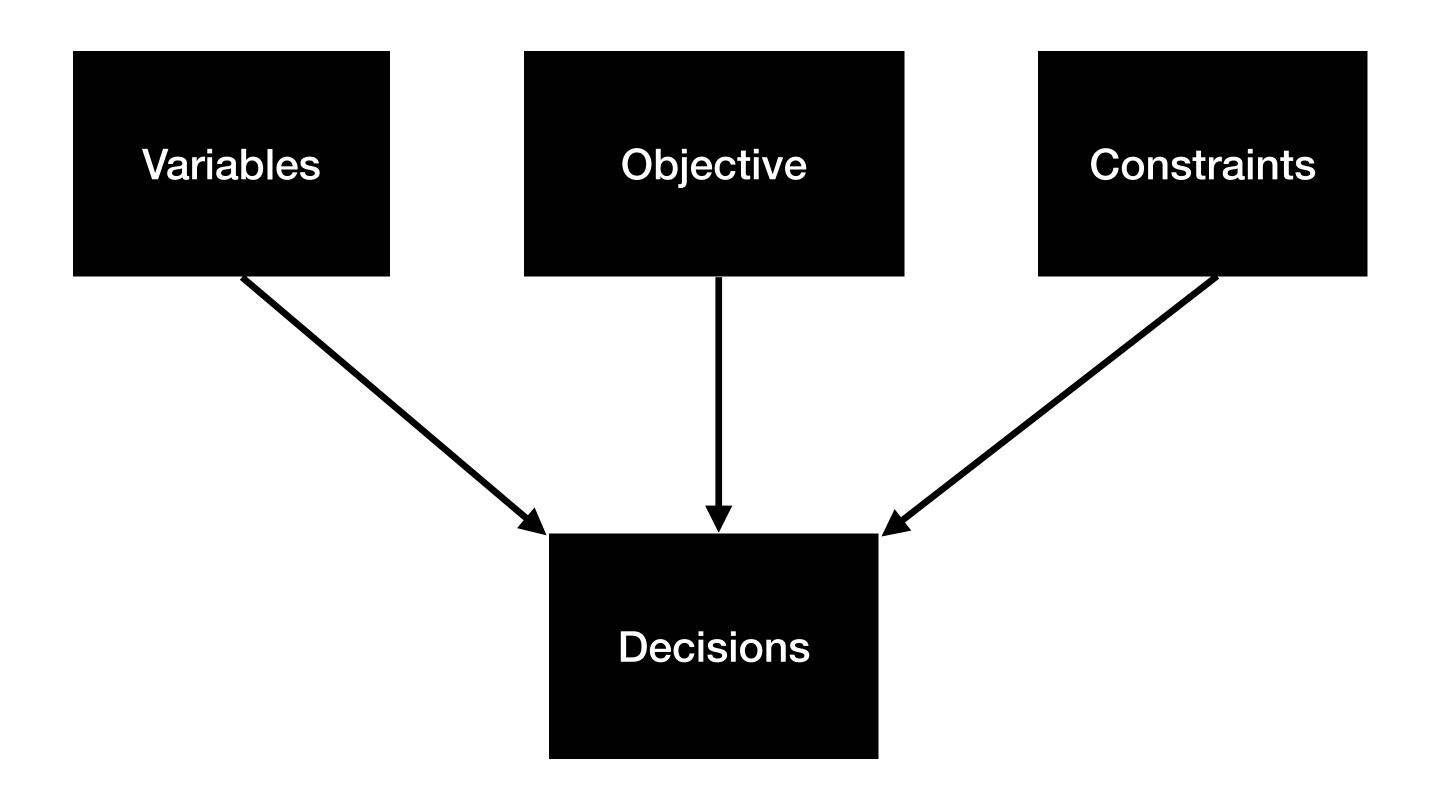
ORF522 – Linear and Nonlinear Optimization

1. Introduction









Finance

Variables

Amounts invested in each asset

Constraints

Budget, investment per asset, minimum return, etc.

Objective

Maximize profit, minus risk



Optimal control

Variables

Inputs: thrust, flaps, etc.

Constraints

System limitations, obstacles, etc.

Objective

Minimize distance to target and fuel consumption



Machine learning

Variables

Model parameters

Constraints

Prior information, parameter limits

Objective

Minimize prediction error, plus regularization



Mathematical optimization

minimize
$$f(x)$$
 subject to $g_i(x) \leq 0, \quad i = 1, \dots, m$

$$x = (x_1, \dots, x_n)$$
 Variables

$$f: \mathbf{R}^n \to \mathbf{R}$$
 Objective function

$$g_i: \mathbf{R}^n \to \mathbf{R}$$
 Constraint functions

$$x^*$$
 Solution/Optimal point

$$f(x^*)$$
 Optimal value

Most optimization problems cannot be solved

Solving optimization problems

General case ——— Very hard!

Compromises

- Long computation times
- Not finding the solution (in practice it may not matter)

Solving optimization problems

General case ——— Very hard!

Compromises

- Long computation times
- Not finding the solution (in practice it may not matter)

Exceptions

- Linear optimization
- Convex optimization

Can be solved very efficiently and reliably

Meet your teaching staff

Instructor



Bartolomeo Stellato

I am a Professor at ORFE. I obtained my PhD from Oxford and I was a postdoc at MIT.

email: <u>bstellato@princeton.edu</u>

office hours: Thu 2pm-4pm EST, Sherred 323

website: stellato.io

Assistant in instruction



Irina Wang

PhD student at ORFE.

email: <u>iywang@princeton.edu</u>

office hours: Mon 1:00pm — 3:00pm EST, at Sherrerd 003

Meet your classmates!

Name? Year?



Meet your classmates!

Name?

Year?

What is your department?

https://www.menti.com/5jp334nxuj



Meet your classmates!

Name?

Year?

What is your department?

https://www.menti.com/5jp334nxuj



What do you want to use optimization for?

Today's agenda

- Optimization problems
- History of optimization
- Course contents and information
- A glance into modern optimization

Linear optimization

minimize
$$c^T x$$
 subject to $a_i^T x \leq b_i, \quad i = 1, \ldots, m$

No analytical formula (99% of the time there will be none in this course!)

Efficient algorithms and software we can solve problems with several thousands of variables and constraints

Extensive theory (duality, degeneracy, sensitivity)

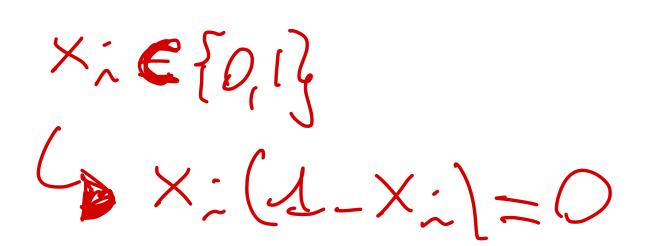
Linear optimization

Example: resource allocation

maximize
$$\sum_{i=1}^n c_i x_i$$
 subject to $\sum_{i=1}^n a_{ji} x_i \le b_j, \quad j=1,\ldots,m$ $x_i \ge 0, \quad i=1,\ldots,n$

- c_i : profit per unit of product i shipped
- b_i : units of raw material j on hand
- a_{ji} : units of raw material j required to produce on unit of product i

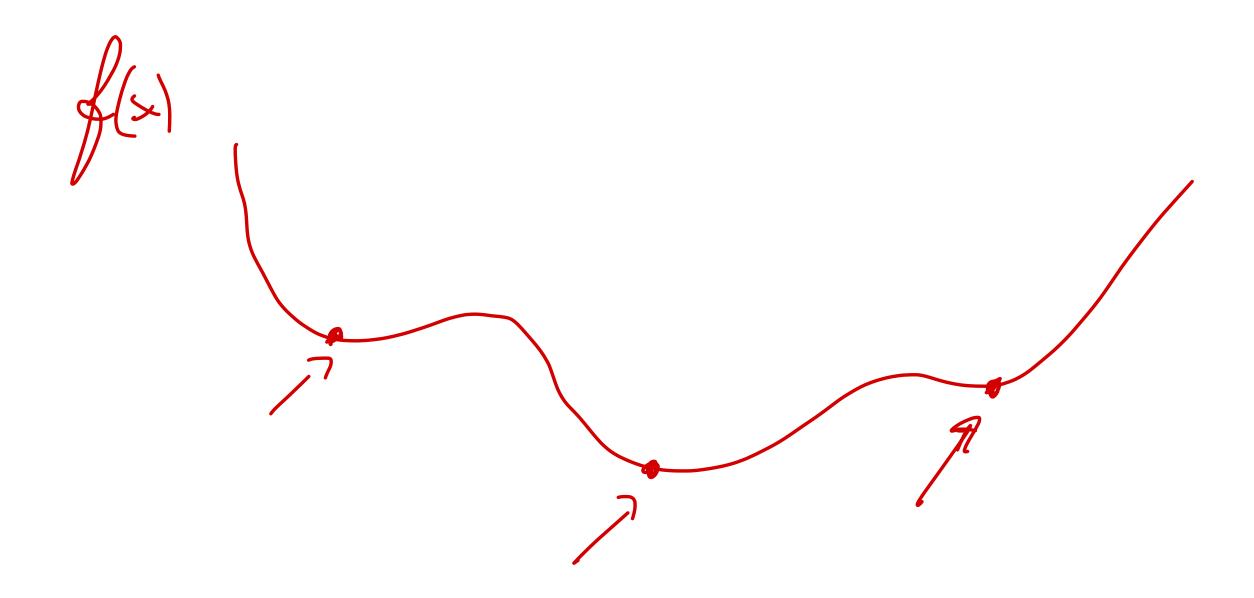
Nonlinear optimization



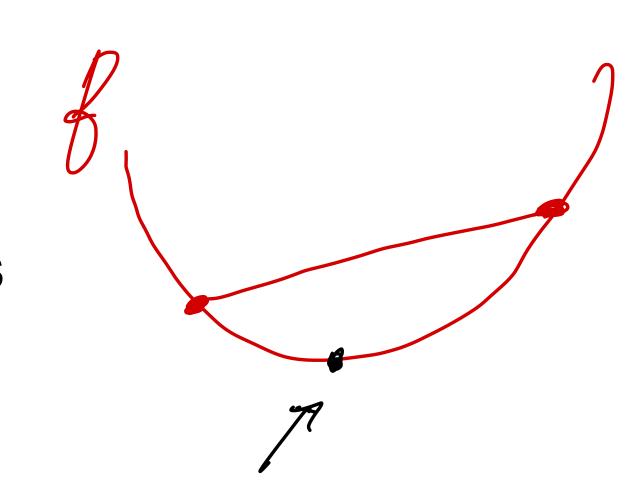
minimize
$$f(x)$$
 subject to $g_i(x) \leq 0, \quad i = 1, \dots, m$

Hard to solve in general

- multiple local minima
- discrete variables $x \in \mathbb{Z}^n$
- hard to certify optimality



Convex optimization



Convex functions

minimize
$$f(x)$$
 subject to $g_i(x) \leq 0, \quad i = 1, \dots, m$

All local minima are global!

Efficient algorithms and software

Extensive theory (convex analysis and conic optimization) [ORF523]

Used to solve non convex problems

Prehistory of optimization

Calculus of variations

Fermat/Newton

minimize $f(x), x \in \mathbf{R}$

$$\frac{\mathrm{d}f(x)}{\mathrm{d}x} = 0$$

Euler

minimize $f(x), x \in \mathbf{R}^n$

 $\nabla f(x) = 0$

Lagrange

minimize f(x)

subject to g(x) = 0

1670

1755

1797

Time

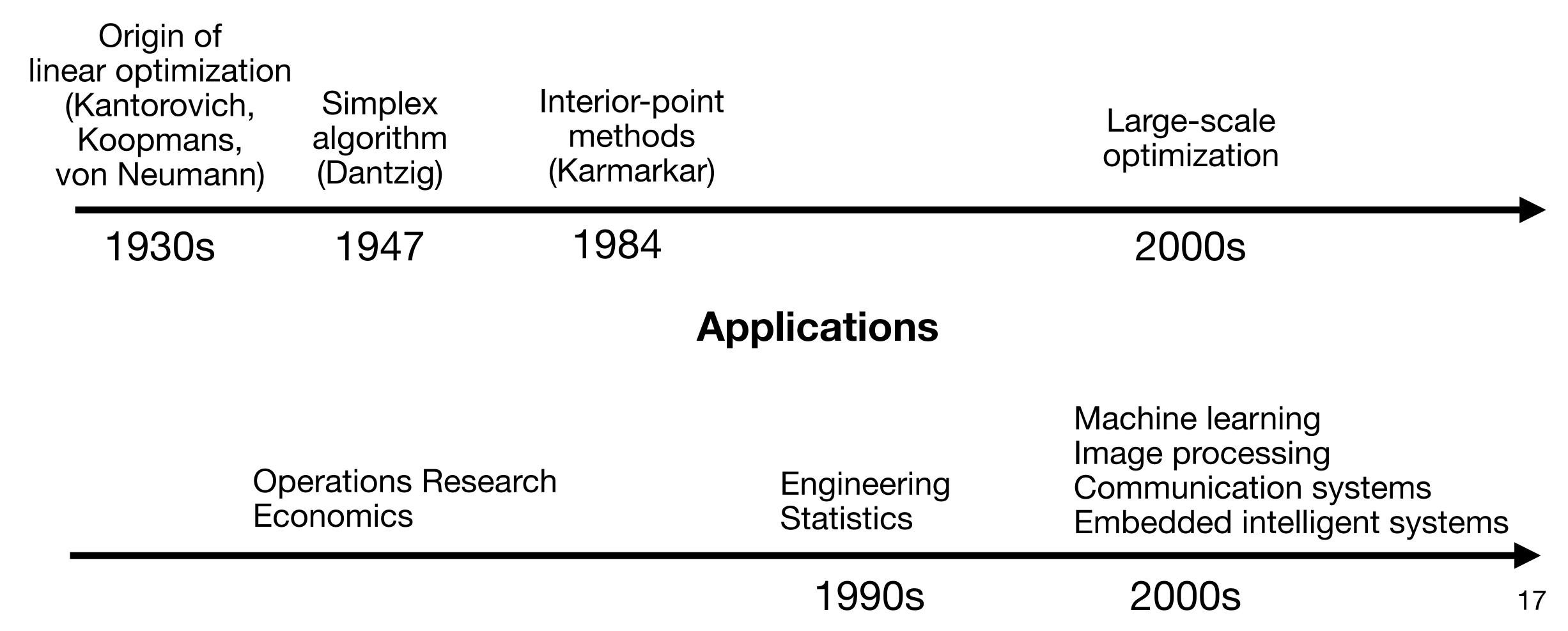
History of optimization

Algorithms

Origin of linear optimization (Kantorovich, Koopmans, von Neumann)	Simplex algorithm (Dantzig)	Interior-point methods (Karmarkar)	Large-scale optimization	
1930s	1947	1984	2000s	

History of optimization

Algorithms



History of optimization

		AI	gorithms	Age of computers					
Origin of linear optimization (Kantorovich, Koopmans, von Neumann)	Simplex algorithm (Dantzig)	Interior-point methods (Karmarkar)		Large-scale optimization					
1930s	1947	1984		2000s					
Applications									
Operations Research Economics			Engineering Statistics	Machine learning Image processing Communication systems Embedded intelligent systems					
			1990s	2000s	17				

Technological innovations

Lots of data



easy storage and transmission

Technological innovations

Lots of data



easy storage and transmission

Massive computations



computers are super fast

Technological innovations

Lots of data



easy storage and transmission

Massive computations



computers are super fast

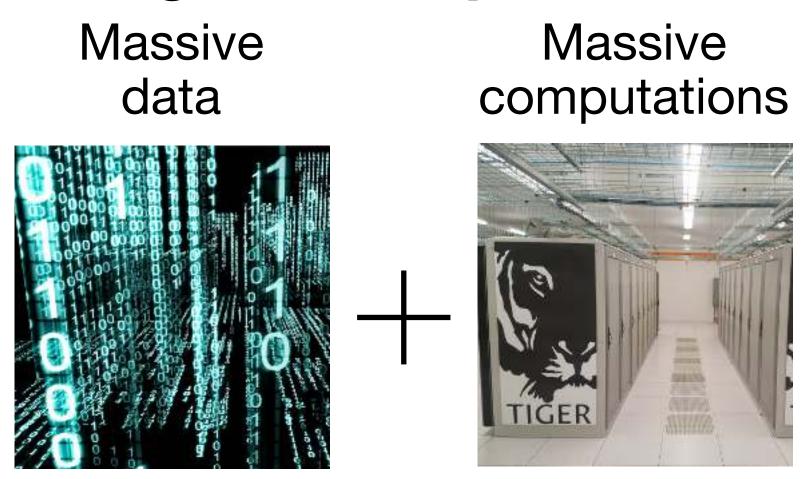
High-level programming languages



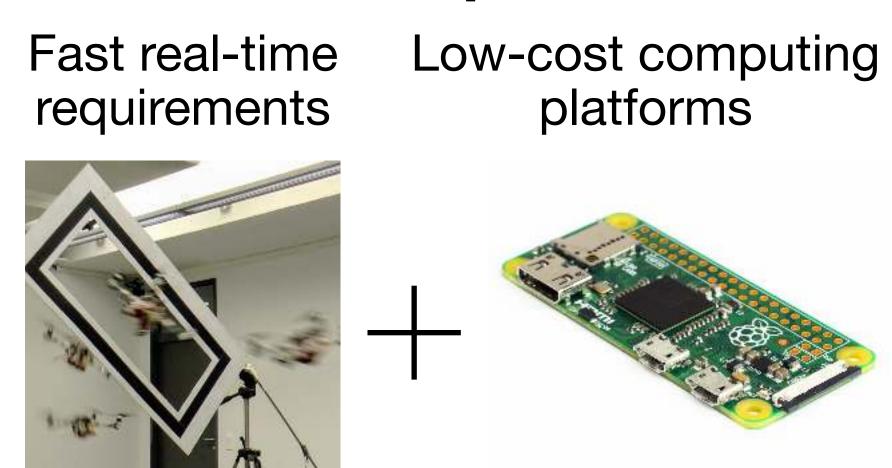
easy to do complex stuff

What is happening today?

Huge scale optimization



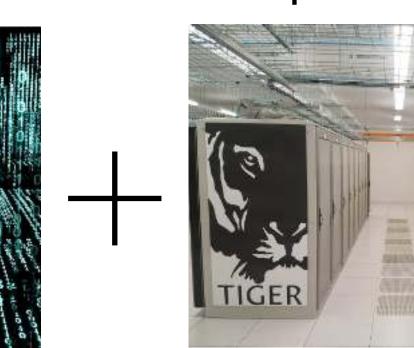
Real-time optimization



What is happening today?

Huge scale optimization

Massive data



Massive computations

Real-time optimization

Fast real-time requirements

Low-cost computing platforms





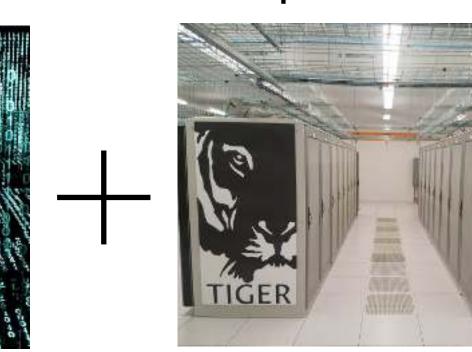
Renewed interest in old methods (70s)

- Subgradient methods
- Proximal algorithms

What is happening today?

Huge scale optimization

Massive data

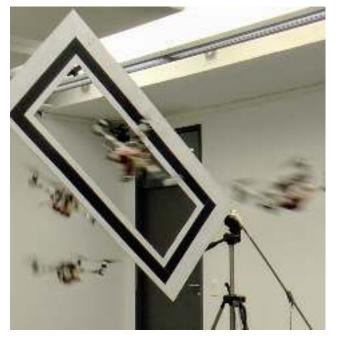


Massive computations

Real-time optimization

Fast real-time requirements

Low-cost computing platforms





Renewed interest in old methods (70s)

- Subgradient methods
- Proximal algorithms

- Cheap iterations
- Simple implementation

Contents of this course

Linear optimization

- Modelling and applications
- Geometry
- Duality
- Degeneracy
- The simplex method
- Sensitivity analysis
- Interior point methods

Nonlinear optimization

- Modelling and applications
- Optimality conditions
- First-order methods
- Operator-splitting algorithms
- Acceleration schemes

Extensions

- Sequential convex programming
- Branch and bound algorithms
- Real-time optimization

Course information

Grading

- 25% Homeworks
 5 bi-weekly homeworks with coding component. Collaborations are encouraged!
- 25% Midterm
 90 minutes written exam . No collaborations. ONLY CIMENT ONLY CI
- 40% Final
 Take-home assignment with coding component. No collaborations.
- 10% Participation
 One question or note on Ed after each lecture.

Course information

10% Participation notes/questions

What?

- Briefly summarize what you learned in the last lecture
- Highlight the concepts that were most confusing/you would like to review.
- Can be anonymous (to your classmates, not to the instructor) or public, as you choose.

Why?

- We will use your ideas to clarify previous lectures, and to improve the course in future iterations.
- You can ask questions you don't feel comfortable asking in class.
- You can use these to gather your thoughts on the previous lecture and solidify your understanding.

Course information

Course website

https://stellato.io/teaching/orf522

Prerequisites

 Good knowledge of linear algebra and calculus.

For a refresher, read Appendices A & C of [CO] Boyd, Vandenberghe: *Convex Optimization* (available **online**).

• Familiarity with Python.



Bartolomeo Stellato

ORF522: Linear and Nonlinear Optimization

Previous years: 2020

Description

This course introduces analytical and computational tools for linear and nonlinear optimization. Topics include linear optimization modeling, duality, the simplex method, degeneracy, sensitivity analysis and interior point methods. Nonlinear optimality conditions, KKT conditions, first order and operator splitting methods for nonlinear optimization, real-time optimization and data-driven algorithms. A broad spectrum of applications in engineering, finance and statistics is presented.

Learning objectives

This course introduces analytical and computational tools for linear and nonlinear optimization. Upon successful completion of this course you should be able to:

- Model decision-making problems across different disciplines as mathematical optimization problems.
- Apply the most appropriate optimization tools when faced with a concrete problem.
- Implement optimization algorithms and prove their convergence.

Course information

Materials

Linear optimization

- [LP] R. J. Vanderbei: Linear Programming: Foundations & Extensions (available on SpringerLink)
- [LO] D. Bertsimas, J. Tsitsiklis: Introduction to Linear Optimization (available Princeton Controlled Digital Lending)

Nonlinear optimization

- [NO] J. Nocedal, S. J. Wright: *Numerical Optimization* (available on **SpringerLink**)
- [CO] S. Boyd, L. Vandenberghe: *Convex Optimization* (available for **free**)
- [FMO] A. Beck: First-order methods in optimization (available on SIAM)
- [FCA] J. B. Hiriart-Hrruty, C. Lemarechal: Fundamentals of Convex Analysis (available on SpringerLink)
- [ILCO] Y. Nesterov: Introductory Lectures to Convex Optimization (available on SpringerLink)
- [e364b] S. Boyd: *Convex Optimization II Lecture Notes* (available **online**)
- [COAC] S. Bubeck: Convex Optimization: Algorithms and Complexity (available for free)
- [MINLO] P. Belotti, C. Kirches, S. Leyffer, J. Linderoth, J. Luedtke, A. Mahajan: *Mixed-integer nonlinear optimization* (available **online**)

Operator splitting algorithms

- [PA] N. Parikh, S. Boyd: *Proximal Algorithms* (available for **free**)
- [PMO] E. K. Ryu, S. Boyd: *A primer on monotone operators* (available for **free**)
- [LSMO] E. K. Ryu and W. Yin: Large-Scale Convex Optimization via Monotone Operators (Draft) (available for free)
- [ADMM] S. Boyd, N. Parikh, B. Peleato, J. Eckstein: Distributed Optimization and Statistical Learning via the Alternating Direction Method of Multipliers (available for free)

Software (open-source)





Numerical computations

Numerical computations on numpy and scipy.

CVXPY

```
\begin{array}{ccc} \text{minimize} & c^T x \\ \text{subject to} & Ax \leq b \end{array}
```

Learning goals

 Model your favorite decision-making problems as mathematical optimization problems.

 Apply the most appropriate optimization tools when faced with a concrete problem.

• Implement optimization algorithms and prove their convergence.

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ———— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

minimize
$$\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^{n} \ell(\hat{y}^i, y^i) + \lambda r(\theta)$$

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

Loss

minimize
$$\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^{n} \ell(\hat{y}^i, y^i) + \lambda r(\theta)$$

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

Loss Regularizer $\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^n \ell(\hat{y}^i, y^i) + \lambda r(\theta)$

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

Loss Regularizer

minimize $\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^{n} \ell(\hat{y}^i, y^i) + \lambda r(\theta)$

Many examples

- Support vector machines
- Regularized regression
- Neural networks

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

Loss Regularizer

minimize
$$\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^{n} \ell(\hat{y}^i, y^i) + \lambda r(\theta)$$

Many examples

- Support vector machines
- Regularized regression
- Neural networks

Large-scale computing

- Parallel
- Distributed

Huge scale optimization

Dataset with billions of datapoints (x^i, y^i) ——— Goal: Design predictor $\hat{y}^i = g_{\theta}(x^i)$

Optimization problem

Loss Regularizer

minimize
$$\mathcal{L}(\theta) + \lambda r(\theta) = \sum_{i=1}^{n} \ell(\hat{y}^i, y^i) + \lambda r(\theta)$$

Many examples

- Support vector machines
- Regularized regression
- Neural networks

Large-scale computing

- Parallel
- Distributed

How large are the largest problems we can solve? (how many variables?)

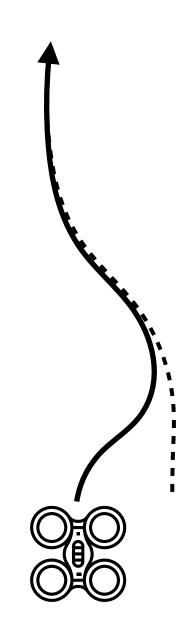
Real-time optimization

Dynamical system: $x_{t+1} = Ax_t + Bu_t$

 $x_t \in \mathbf{R}^n$: state $u_t \in \mathbf{R}^m$: input

Goal: track trajectory minimize $\sum_{t=0}^{\bar{}} \|x_t - x_t^{\mathrm{des}}\|$

Constraints: inputs $||u|| \leq U$, states $a \leq x_t \leq b$



Real-time optimization

Dynamical system: $x_{t+1} = Ax_t + Bu_t$

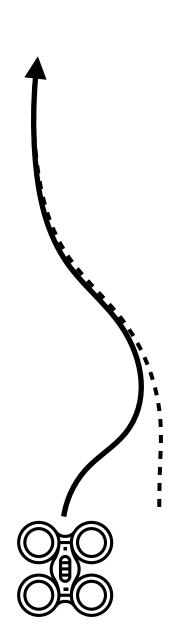
 $x_t \in \mathbf{R}^n$: state $u_t \in \mathbf{R}^m$: input

Goal: track trajectory minimize $\sum_{t=0}^{\bar{}} \|x_t - x_t^{\mathrm{des}}\|$

Constraints: inputs $||u|| \le U$, states $a \le x_t \le b$



How fast can we solve these problems?



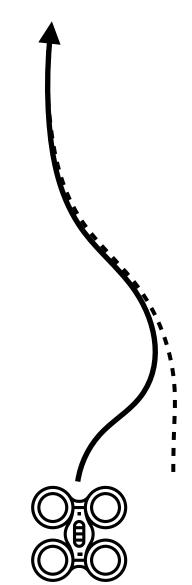
Real-time optimization

Dynamical system: $x_{t+1} = Ax_t + Bu_t$

 $x_t \in \mathbf{R}^n$: state $u_t \in \mathbf{R}^m$: input

Goal: track trajectory minimize $\sum_{t=0}^{-} \|x_t - x_t^{\text{des}}\|$

Constraints: inputs $||u|| \le U$, states $a \le x_t \le b$



Solve and repeat.....

How fast can we solve these problems?

1-norm → ???

Real-time optimization

Dynamical system: $x_{t+1} = Ax_t + Bu_t$

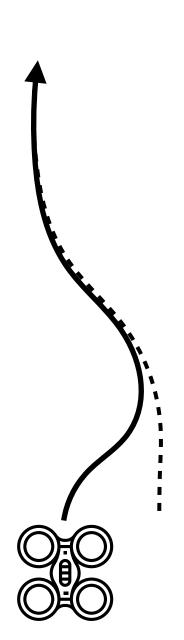
 $x_t \in \mathbf{R}^n$: state $u_t \in \mathbf{R}^m$: input

Goal: track trajectory minimize $\sum_{t=0}^{\bar{}} \|x_t - x_t^{\mathrm{des}}\|$

Constraints: inputs $||u|| \le U$, states $a \le x_t \le b$



How fast can we solve these problems?



Next lecture Linear optimization

- Definitions
- Modelling
- Formulations
- Examples